

UNITED STATES PATENT APPLICATION

for

VIRTUALIZED STRIPING CONTROLLER

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VIRTUALIZED STRIPING CONTROLLER

FIELD OF THE INVENTION

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The invention is generally directed at a low cost approach to gaining higher performance from disk drives by striping.

DESCRIPTION OF THE PRIOR ART

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Parallel transfer drives were the first effort at gaining hard disk performance by making parallel accesses. In a parallel transfer drive, data is written and read simultaneously off of multiple platters in a single housing. But parallel transfer drives, while fast, are very expensive.

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The concept of striping was developed to achieve the advantages of parallel transfer drives at a much lower cost by combining two totally separate, low-cost drives with sophisticated software. Striping creates a single virtual disk from two physical drives. The sectors of the two physical disks are interleaved on the virtual drive. The effect is that the virtual disk has double the capacity of a single disk and double the data transfer rate of a single disk drive since the two

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physical drives can be read and written in parallel.

Figure 1 is a schematic that illustrates the basic concept of striping. Referring now to Figure 1, a virtual drive 3 is a model of the striped physical drives 4 and 5. Physical drives 4 and 5 are separate disk drives each having its own set of drive electronics 6 power supplies and

mirrors (not shown) and disks which in this example are single disks 7a and 7b. Each disk is divided into tracks and each track is divided into sectors. For purposes of illustration, each disk is shown as having 8 sectors (numbered 0-7). Sectors 0-7 on physical drive 4 correspond to sectors 40 - 47 on virtual disk 3. And sectors 0 - 7 on physical drive 5 correspond to sectors 50-57 on virtual disk drive 3. Striping creates a new interface which is indicated at reference numeral 2 in Fig. 1.

Striping was first introduced in SCSI (Small Computer System Interface) drives for work stations. The original motivation for striping was to gain more performance in the work station environment where performance was previously limited to a data transfer rate of 10 megabits per second that was mandated by a drive rotating at 3600 rpm and having 17 sectors of 512 bytes per track.

Later, the basic striping technology developed for SCSI drives was applied to the integrated drive electronics ("IDE") drive. This transition was motivated by the even lower cost and wider adoption of the IDE drive in the Industry Standard Architecture ("ISA") based computer (IBM compatible) market. But these drives still used the architecture developed in the SCSI interface environment to implement the striping IDE drive which relies on a dedicated microprocessor.

These IDE controllers stripe the data by simultaneously reading data from the primary and secondary IDE channels. Software drivers are then used to encode and decode the striped data streams. In this approach, there is a maximum of four physical disk drives and two logical

drives per IDE interface. Each logical disk drive is mapped to two physical disk drives through a sophisticated software driver.

An IDE hard disk drive integrates both a hard disk drive and its controller in one unit -
5 inside the drive housing. An IDE drive appears to the host computer as two blocks of I/O
(input/output) registers, a command register block and a control register block, with addresses in
the I/O space of the ISA bus. The IDE drive interfaces to an ISA or PCI (Peripheral Component
Interconnect) bus. The interface between an IDE drive and the system bus, sometimes called a
host adapter, is typically a small card that plugs into the ISA bus. On the IDE side of the card, a
10 40 pin ribbon cable leads to the remainder of the IDE electronics. The IDE interface essentially
reduces the width of the ISA bus by eliminating the ISA address lines and substituting two
commands, CS1FX and CS3FX, which select respectively the command register block or the
control register block from an ISA bus address. Parallel data is supplied to the IDE interface
where it is converted to serial data, converted to analog and written on the media in specified
15 locations called addresses. IDE electronics detect errors through the addition of error detection
algorithms added to each sector. But the IDE electronics typically do not correct errors. Rather,
the IDE drive passes raw error data back to the host for correction.

The IDE specification limits the sector per track to 64; the tracks to 2048 per disk, 16
20 heads per disk and 2 drives per interface. A PC (Personal Computer) type computer system can
have two IDE interfaces. That is, two channels are located at two different addresses in I/O
space. In a standard computer using an IDE interface, this means that it is possible to hook up a
maximum of four physical drives conventionally.

The problem with the prior art approaches is that the standard IDE software drivers cannot be used, and special device drivers must be written for each operating system. In addition, the hardware is expensive since an additional microprocessor is required.

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SUMMARY OF THE INVENTION

Sub A, } The present invention is a striping disk controller used in a computer system that includes a CPU connected to a system bus and running an operating system and having a BIOS. A disk drive interface is connected to the system bus and communicates with the BIOS. First and second disk drives are provided, each including analog electronics, data separator electronics, formatting electronics and head positioning electronics. A striping controller is connected between the first and second disk drives and the interface. The striping controller causes data being communicated between the system bus and the first and second drives to be written and read to and from the first and second dries substantially in parallel, alternating sectors on each drive. Striping increases data transfer rates by accessing two drives simultaneously. During read and write operations, both drives are accessed simultaneously which has the effect of doubling the effective transfer rate and capacity.

BRIEF DESCRIPTION OF THE DRAWING

The preferred embodiment will be described in connection with the Drawing in which:

Figure 1 is a schematic of a virtual disk.

5 Figure 2 is a process flow chart showing how disk accesses are made in a conventional IDE system.

Figure 3 is a schematic of the data structure of a system request for access to an IDE drive.

Figure 4 is a block diagram of a prior art striping system.

10 Figure 5 is a high-level block diagram of the present invention as applied to two virtual disk drives, and four physical drives.

Figure 6 is a schematic of the system request data structure broken out into its component parts and showing how bits are shifted according to the invention.

15 Figure 7 is an illustration of an example of how the mapping set out in Figure 6 effects striping.

20 Figure 8 is a schematic of a preferred embodiment of a striping controller according to the present invention.

Figure 9 is a table indicating how virtual sector starting addresses and sector counts are mapped to physical starting address and counts.

DESCRIPTION OF THE PREFERRED EMBODIMENT

The present invention is a striping disk controller used in a computer system that includes a CPU connected to a system bus and running an operating system and having a BIOS (Basic Input/Output System). In the following description, for purposes of explanation, numerous specific details are set forth in order to provide a thorough understanding of the present invention. It will be evident, however, to one of ordinary skill in the art that the present invention may be practiced without these specific details. In other circumstances, well-known structures and devices, and interfaces are shown in block diagram form in order to avoid unnecessarily obscuring the present invention.

Figure 2 is a process flow chart showing how disk accesses are made in a conventional IDE system. In process block 20 a requirement for X bytes of storage is generated by an application. The application passes this request to the operating system 22. Operating system 22 translates the application request to a file system request. In the case of conventional DOS (Disk Operating System), the file system request includes an identity of "virtual sectors", which are incremented corresponding to the disk track and head. That is, the zero sector of track 2 is one virtual sector higher than the last physical sector on track 1. A Basic Input/Output Operating System (BIOS) is a set of machine language routines, usually found in a ROM (read only memory) on the mother board, that work with I/O interfaces at the lowest level and thereby relieve higher level code of this task. In the case of disk storage, the BIOS translates virtual sector requests received from the operating system into the physical IDE requests at process step 24. Physical IDE request means a request for a specific sector, a specific track, a specific head

and a specific drive. The physical request is made in compliance with the IDE specification and supplied to IDE interface 26 which decides the drive request and passes on the sector, track and head requests either over bus 28 to IDE drive 30 or over bus 32 to IDE drive 34. Each IDE drive contains conventional IDE electronics 36 and a disk assembly 38 of one or more disks up to 16 surfaces. IDE electronics 36 performs several functions: It translates a request for access request supplied from the BIOS to specific physical sectors, tracks and heads on disk 38. It also performs data separation which on reads generates a clock and digital data signal in serial format. It also performs formatting functions, namely serial to parallel conversion on reads and parallel to serial on writes. It also performs head positioning and analog data functions.

Figure 3 is a schematic of the data structure of a system request for access to an IDE drive that is relevant to the present invention. It is generally that portion which relates to a particular disk and the location on that disk that specific data is to be written or read. Referring now to Figure 3, a system access request structure 40 consists of a sector request bit string 42 of 6 bits that can uniquely identify 64 sectors; a track request bit string 44 of 11 bits that can uniquely identify 2048 tracks; a head request bit string of 4 bits that can uniquely identify 16 heads and a drive bit 48 that can identify 2 drives. Enhanced IDE (EIDE) will increase the allowable tracks. It will be apparent to those of ordinary skill in the art that equivalent variations of basic IDE may be implemented without departing from the scope of the present invention.

Figure 4 is a block diagram of a prior art striping system. Referring to Figure 4, the two IDE interfaces 50 and 52 are connected via busses 54 and 56 to striping controller 58. A microprocessor 60 is connected by bus 62 to striping controller 58. Microprocessor 60 runs the code that determines the type of striping action - e.g. interleaving the two disk drives to get better performance or mirroring for better redundancy. Buffer memory 64 stores some of the code for microprocessor 60 and acts as a cache for microprocessor 60. Microprocessor 60 is also interfaced to a host computer system across bus 66 such as ISA or PCI bus. The IDE electronics returns status and error signals to microprocessor 60. Microprocessor 60 performs error correction and returns status and error messages to the host. Thus, part of the function of microprocessor 60 is to manage the status and error signals from two different physical disk drives and report only one status and error to the host. The host believes that there is only one hard disk drive with twice the performance and twice the capacity, while in fact there are two disk drives that are interleaved.

The output from striping controller 58 on busses 54 and 56 are compliant to the IDE specification since they connect to IDE interfaces 50 and 52. Striping logic 58 performs the functions of translating the microprocessor 60 requests into the two physical IDE buses.

In this implementation, the disk drive does not look like an IDE drive to the host. Rather a disk access looks like a host to host communication. From an operating system perspective, this means that the standard IDE software driver cannot be used.

Figure 5 is a high-level block diagram of the present invention as applied to a single IDE

interface. Referring now to Figure 5, system bus 66 is connected to IDE interface 26. System bus 66 may be an ISA or PCI bus, for example. IDE Bus 28 connects IDE interface 26 to the host computer side of a striping IDE controller 70. The disk drive side of IDE controller 70 is connected by IDE bus 72 to IDE drive 30 and by IDE bus 74 to a second IDE drive 76. A similar
 5 configuration consisting of a second striping IDE controller 78 and IDE drives 82 and 84 may but need not be connected to a second IDE bus 32. Each IDE drive, 30, 76, 82 and 86 contain conventional IDE electronics 36 and a disk assembly 38.

When a system access request is received by the striping controller 70, the request is translated into two requests for two physical drives in an interleaving fashion such that even sectors in the system access request are accessed on one physical disk drive, for example drive 30 and odd sector in the system access request are accessed on disk drive 76. This is accomplished by mapping of the bits in the system request into two physical drive requests.

Referring now to Figure 6, the least significant bit, that is the 0 bit in sector string 42 of system request 40 is mapped to the drive select bit 92 of drive request 90. Bit 1 of sector request 42 is mapped to bit 0 of sector request 94 of drive request 90 and so forth. This leaves the most significant bit (msb), that is bit 5 of sector select string 92, open. This position is taken by the least significant bit (lsb), that is bit 0, of track select string 44 of system request 40. Bit 1 of track select string 44 is mapped to bit 0 of track request string 96 of drive request 90 and so forth. This leaves the msb, that is bit 10 of track select string 96, open. This position is taken by the least significant bit, that is bit 0, of head select string 46 of system request 40. Bit 1 of head select string 46 is mapped to bit 0 of head request string 98 of drive request 90 and so forth. This

leaves the msb, that is bit 3 in the preferred embodiment of head request string 98 open. This position is not filled in the preferred embodiment.

Because a Personal Computer (PC) system has two IDE interfaces at two different input/output (I/O) addresses and each IDE interface can access two disk drives, there are a maximum of eight physical hard disks that can be mapped to four logical disks with the present invention.

Figure 7 illustrates an example of how the mapping set out in Figure 6 creates striping. Referring now to Figure 7, the operating system makes a request for 8 sectors starting with sector 33. The binary address of each sector is set out in table 1 of the example shown in Figure 7. According to the invention, the sector request is shifted right by one bit. This causes the least significant bit to drop out of the address and therefore this bit can be used for something else. In the present invention, this bit is used to select the drive. Thus, in sector 33 where the least significant bit is set to 1, that request would map to drive 1. That is, the ¹⁰⁰⁰⁰¹~~600001~~ address would drop the last 1 and make a sector request for ¹⁰⁰⁰⁰⁰~~600000~~ which amounts to a request for sector 16 on drive 1. For sector 34, which is binary address ¹⁰⁰⁰¹⁰~~600010~~, the least significant bit is 0 which is interpreted such that request goes to drive 0. The address is for sector 17 on drive 0. Other addresses are mapped similarly. The next request would be a request for sector 17 from drive 1. The next request would be for sector 18 from drive 0. Then sector 19 from drive 1. etc.

Figure 8 is a schematic of a preferred embodiment of a striping IDE controller according to the present invention. Referring now to Figure 8, striping IDE controller 70 has exclusive OR

("XOR") gate 200 with inputs 202 and 204, both of which are connected to IDE interface 26. Input 202 is connected through interface 26 to the LSB of the current sector address. Input 204 is the least significant bit from the first sector to be transferred. (In an XOR gate, the output is enabled if either of the inputs is enabled but both inputs are not enabled.) The output 206 of XOR 200 is connected to gating input 208 of first-in-first-out ("FIFO") memory 210. Output 206 of XOR 200 is also connected to the input of inverter 212. The output of inverter 212 is connected to gating input 214 of FIFO memory 216. FIFO memories 210 and 216 may be 32kx8 static random access memories (SRAM). Bus 218 includes 16 data lines which carry 16 bits (two bytes) of data in parallel from IDE interface 26 and supplies it simultaneously to data inputs 220 and 222 of FIFO memories 210 and 216. However, gating inputs 208 and 214 operate such that FIFO 210 and 216 memories only receive data when the gating input is activated. The outputs of FIFO memories 210 and 216 are connected to IDE disk drives 30 and 76 respectively by data busses to the respective IDE drive. Figure 8 is a physical implementation of Figure 7. Operationally, Figure 8 translates alternating sector requests to alternating disk drives.

Figure 9 illustrates an example of how virtual sector starting addresses and sector counts are mapped to physical starting addresses and counts. Referring to Figure 9, S_0 and S_1 refer to starting sector addresses. When the address is even, each physical drive (Dr_0 and Dr_1) are provided addresses exactly one-half of the virtual (system) address. When an odd starting address is provided, Dr_0 is provided an address rounded up and Dr_1 is provided an address rounded down.

C_0 and C_1 refer to sector count. When the count is even, both physical drives (Dr_0 and

Dr₁) are provided counts exactly one-half of the virtual (system) count. When the count is odd, Dr₀ is rounded up if the starting address is even; Dr₀ is rounded down for odd starting addresses. Dr₁ is rounded down when Dr₀ is rounded up; Dr₁ is rounded up when Dr₁ is rounded down.

5 The design of the present invention as described above according to its preferred embodiment achieves the goals of striping (doubling disk throughput B₁ accessing two drives simultaneously) with minimal hardware (most other designs require a microprocessor and or ASIC) and an interface which appears to the operating system as standard IDE interface. Other implementations require custom drivers.

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